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@ GMMTest.GAU: Check diff between 'full' GMM, limited GMM, and iterated GMM @  

@ Ruth Judson, Feb 1996 @  

@ Model is Yit = GAMMA * Yit-1 + Xit * BETA + ETAi + EPSILONit @  

@     where Xit = RHO * Xit-1 + XIit @  

@     XI~N(0,SigXi), EPSILON~N(0,SigE) @  

@ Here SigE is normalized to 1, and RHO is always 0.5 @  

@ Xit is not constructed to be correlated with ETAi, but usually is, hence LSDV@  

@ BETA is set to be 1-GAMMA so that the long-run multiplier is 1. GAMMA=0.2,0.8@  

@ SigETA is set as MU*SigEP*(1-GAMMA) so that for MU=1, effect of EPS and ETA=@  

@ SigS is defined as Var(RHS)-Var(error), the variance of the signal @  

@ SigS and other pars determine SigXi as in Eq 41. @  

@ Here we also use AH to estimate gamma and compare bias/SE properties @  

@ Note that when the feasible Kiviet correction is used, a consistent est of @  

@ gamma, e.g. from AH, is needed @  

@ Kiv3 does GMM as well as AH and LSDV @  

@ Kiv4 does limited GMM--max of 10 instruments @  

@ Kiv5 does correction using GMM1 as initial consistent estimates @  

@ Note that iterative GMM might be better @  

@ Kiv6 uses iterative restricted GMM to get initial cons. estimates @  

@ GMMTest compares various forms of GMM--restricted, iterative, GMM1, GMM2 @  

@ GMM8s used fixed seed @  

@ GMM9 uses past and future values for instruments @  

@     Numbers of instruments are 1,3,7,9 @  

@-----@  

new;  

time0=hsec;  

clear bgmm13,bgmm15,bgmm17,bgmm23,bgmm25,bgmm27,m;  

  

output file=gmm9chk.out reset; outwidth 200;  

  

@ Set basic parameters: N T Gamma SigE Mu SigS Rho @  

ncase=64; npar=7;  

load parmat[ncase,npar]=parmat.asc;  

load seeds[1100,3]=seeds.asc;  

  

ncase=rows(parmat);  

npar=cols(parmat);  

ndraw=1000;  

nstart=50;  

@ let mvals= 3 5 7; @  

let mvals= 3    7;          @ Max # of inst (m=t-2 is full GMM) @  

k2;  

@ nest=2*rows(mvals);@  

nest=rows(mvals);  

  

"GMMTest: Estimation of GMM restricted to 1, 3 ,5, and 7 instruments";  

format /rds 1,0; "NDraw=";;ndraw; "NStart=";;nstart;"Sige=1";  

@ " T \t N \tSgs\tMu \tPar\t Stat \tGMM13 \tGMM15 \tGMM17 \tGMM23 \tGMM25 \tGMM27";@  

@ " T \t N \tSgs\tMu \tPar\t Stat \tGMM13 \tGMM17";@  

ic50=int(ndraw*0.5);  

ic05=int(ndraw*0.05)+1;  

ic25=int(ndraw*0.25);  

ic75=int(ndraw*0.75);  

ic95=int(ndraw*0.95);  

nstat=8;  

let statnam= mean stdev median rmse pct05 pct25 pct75 pct95;  

  

icase=1; do until icase>ncase;  

  "Working on case ";;format /rdn 1,0; icase;  

  outmatg=zeros(nstat,nest);  

  outmatb=zeros(nstat,nest);  

  time0=hsec;

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pvec=parmat[icase,.];
n=pvec[1]; t=pvec[2]; gam=pvec[3]; sige=pvec[4];
mu=pvec[5]; sigs=pvec[6]; rho=pvec[7];
rho=0.5;
mvec=miss(zeros(n,1),0);
bvec=zeros(ndraw,nest);
gvec=zeros(ndraw,nest);

beta=1-gam;
sigeta=mu*sige*(1-gam);
sigxi2 = (1/beta^2)*(sigs - (gam^2/(1-gam^2))*sige^2)*
          (1 + ((gam+rho)^2/(1+gam*rho))*(gam*rho-1) - (gam*rho)^2);
sigxi=sqrt(sigxi2);

@ Form set matrices for docorr @
atmat=eye(t-1) - (1/(t-1))*ones(t-1,t-1);
qvec=ones(1,1)|zeros(k-1,1);

@ Form X here since it is not replicated every run
screen on; output off;
idraw=1; do until idraw>ndraw;
@ if idraw/100 == int(idraw/100); "*"; else; ".";
endif;@
if idraw/100 == int(idraw/100); "*"; endif;
gosub makex;
gosub draw1;
gosub dogmm;
gvec[idraw,.]=bgmm13[1]~bgmm15[1]~bgmm17[1]~bgmm23[1]~bgmm25[1]~bgmm27[1];@
bvec[idraw,.]=bgmm13[2]~bgmm15[2]~bgmm17[2]~bgmm23[2]~bgmm25[2]~bgmm27[2];@
gvec[idraw,.]=bgmm13[1]~bgmm17[1];
bvec[idraw,.]=bgmm13[2]~bgmm17[2];
idraw=idraw+1; endo;

screen on; output on;
print;
=====
@ In new format with fixed seed, print as follows
@ For each set of parameters, estimator results across
@ Under mean for each estimate, SE, median, 5th, 25th, 75th, 95th percentile
@ Outmat holds results for only one case at a time, then is cleared
@ Have to loop twice: once to fill outmat by col, then once to print by row
=====
iest=1; do until iest>nest;
    ghold=sortc(gvec[.,iest],1);           bhold=sortc(bvec[.,iest],1);
    gbias=ghold-gam;                     bbias=bhold-beta;
    outmatg[1,iest]=meanc(gbias);         outmatb[1,iest]=meanc(bbias);
    outmatg[2,iest]=stdc(ghold);          outmatb[2,iest]=stdc(bhold);
    outmatg[3,iest]=ghold[ic50]-gam;      outmatb[3,iest]=bhold[ic50]-beta;
    outmatg[4,iest]=sqrt(meanc((gbias.*gbias)));
    outmatb[4,iest]=sqrt(meanc((bbias.*bbias)));
    outmatg[5,iest]=ghold[ic05]-gam;      outmatb[5,iest]=bhold[ic05]-beta;
    outmatg[6,iest]=ghold[ic25]-gam;      outmatb[6,iest]=bhold[ic25]-beta;
    outmatg[7,iest]=ghold[ic75]-gam;      outmatb[7,iest]=bhold[ic75]-beta;
    outmatg[8,iest]=ghold[ic95]-gam;      outmatb[8,iest]=bhold[ic95]-beta;
iest=iest+1; endo; print;

"Gamma results, case "; format /rdt 3,0; icase;
t;;n;;sigs;;mu;;format /rdt 3,1; gam;;
istat=1; do until istat>nstat;
    if istat>1; " \t \t \t \t \t"; endif;
    format /rdt 6,6; $statnam[istat];; format /rdt 6,3; outmatg[istat,.];
istat=istat+1; endo;

"Beta results, case "; format /rdt 3,0; icase;

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t;;n;;sigs;;mu;;format /rdt 3,1; beta;;
istat=1; do until istat>nstat;
    if istat>1; " \t \t \t \t"; endif;
    format /rdt 6,6; $statnam[istat];; format /rdt 6,3; outmatb[istat,.];
istat=istat+1; endo;
"Time to run ";; format /rds 1,0; ndraw;; "draws=";
format /rdn 8,2; (hsec-time0)/6000;; " minutes";
endcase;
icase=icase+1; endo;
stop;
end;
=====
@ Subroutines:
@ MakeX creates the X variable
@ DRAW1 creates the data
@ DoReg does the regression
@ DoAH does Anderson-Hsiao IV estimation (consistent, but big SEs)
@ DoCorr calculates the correction
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@ MAKEX
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makex:

ss=seeds[idraw,1];
ximat=sigxi*rndns(t+nstart,n,ss);

x=zeros(t+nstart,n);
x[1,.]=ximat[1,.];
ii=2; do until ii>t+nstart;
    x[ii,.]=rho*x[ii-1,.] + ximat[ii,.];
ii=ii+1; endo;

dx=mvec'\(x[2:t+nstart,.]-x[1:t+nstart-1,.]);
x=x[1:t+nstart,.];

return;
end;

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@ DRAW1
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draw1:

ss=seeds[idraw,2];
eta=sigeta*rndns(n,1,ss);

ss=seeds[idraw,3];
epsmat=sige*rndns(t+nstart,n,ss);

y=zeros(t+nstart,n);
y[1,.]=epsmat[1,.] + x[1,.] + eta';
ii=2; do until ii>t+nstart;
    y[ii,.]=gam*y[ii-1,.] + beta*x[ii,.] + epsmat[ii,.] + eta';
ii=ii+1; endo;

dy=mvec'\(y[nstart+2:t+nstart,.]-y[nstart+1:t+nstart-1,.]);
dylag=vec(mvec'\dy[1:t-1,.]);
dy=vec(dy);

ylag=mvec'\y[nstart+1:t+nstart-1,.];
ylag2=vec(mvec'\ylag[1:t-1,.]);
ylag=vec(ylag);

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dx=mvec' | (x[nstart+2:t+nstart,.]-x[nstart+1:t+nstart-1,.]);
yvec=vec(y[nstart+1:t+nstart,.]);
dxvec=vec(dx);
xvec=vec(x[nstart+1:t+nstart,.]);

return;
end;
@-----
@ DoGMM
@ Do Arellano-Bond GMM1 and GMM2
@ Do GMM1 and GMM2 for m=3 and m=5
@-----
dogmm:
yreg=dy; xreg=dylag~dxvec;
xx=packr(yreg~xreg);
yreg=xx[.,1]; xreg=xx[.,2:cols(xx)];
@ output on; format /rds 10,6; "Y=";;yvec; "X=";xvec;@
@-----
@ Now do restricted GMM @
@-----
im=1; do until im>rows(mvals); m=mvals[im];

xcol=m*(t-2) - (1/8)*(m^2 - 1);
if m>6; if t==5; xcol=14; else; xcol=xcol-(1/2)*(m-6)*(m-5); endif; endif;

if t>m+2; ycol=(1/2)*m*(m+1) + m*(t-m-2); else; ycol=(1/2)*(t-2)*(t-1); endif;

zcol=xcol+ycol;

amat=zeros(zcol,zcol);                                @ First-stage weighting matrix  @
hmat=2*eye(t-2);                                    @ Amat is sum over n z'hz inv.  @
xprimez=zeros(cols(xreg),zcol);
zprimey=zeros(zcol,1);

@ The loop below fills zmat @
in=1; do until in>n;
    ix1=(in-1)*t+1; ix2=in*t;
    in1=(in-1)*(t-2)+1; in2=in*(t-2);
    zzkount=0;
    zmat=zeros(t-2,zcol);
    it=1; do until it>t-2;
        if it<=m;
            zmat[it,zzkount+1:zzkount+it]=yvec[ix1:ix1+it-1]';
            zzkount=zzkount+it;
            if it<(1/2)*(m-3); iz1=ix1; else; iz1=ix1+it+1-(1/2)*(m-1); endif;
            if t-it<(1/2)*(m+3); iz2=ix2; else; iz2=ix1+it+1+(1/2)*(m-1); endif;
            iz=iz2-iz1+1;
            zmat[it,zzkount+1:zzkount+iz]=xvec[iz1:iz2]';
            zzkount=zzkount+iz;
        else;
            zmat[it,zzkount+1:zzkount+m]=yvec[ix1+it-m:ix1+it-1]';
            zzkount=zzkount+m;
            if it<(1/2)*(m-3); iz1=ix1; else; iz1=ix1+it+1-(1/2)*(m-1); endif;
            if t-it<(1/2)*(m+3); iz2=ix2; else; iz2=ix1+it+1+(1/2)*(m-1); endif;
            iz=iz2-iz1+1;
            zmat[it,zzkount+1:zzkount+iz]=xvec[iz1:iz2]';
            zzkount=zzkount+iz;
        endif;
        if in==1 and it>1; hmat[it,it-1]=-1; hmat[it-1,it]=-1; endif;
    it=it+1; endo;
amat=amat + zmat'*hmat*zmat;
xprimez=xprimez + xreg[in1:in2,.]'zmat;
zprimey=zprimey + zmat'yreg[in1:in2];

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return;  
end;
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